Module 7: Binary Search

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Binary Search

- Binary search is a Θ(log n), highly efficient search algorithm, in a sorted array.
- It works by comparing a search key K with the array's middle element A[m]. If they match, the algorithm stops; otherwise, the same operation is repeated recursively for the first half of the array if K < A[m], and for the second half if K > A[m].
- The number of comparisons to search for a key in an array of size n is C(n) = C(n/2) + 1, for n > 1. C(n) = 1 for n = 1.

$$\underbrace{A[0] \dots A[m-1]}_{\text{search here if}} \underbrace{A[m] \underbrace{A[m+1] \dots A[n-1]}_{\text{search here if}} A[m]}_{\text{K} > A[m]}$$

Binary Search

Example

| | Searc K = 70 | - |
|-----|-----------------|-----|
| I=0 | r=12 | m=6 |
| l=7 | r=12 | m=9 |
| I=7 | r=8 | m=7 |

return -1

```
index
                           3
                                    5
                                                8
                                                     9
                                                        10
                                                            11
                                                                 12
    value
                      27
                          31
                               39
                                   42
                                       55
              3
                  14
                                            70
                                                74
                                                             93
                                                                 98
iteration 1
                                                                  r
iteration 2
                                                     m
                                                                  r
iteration 3
                                           l.m r
```

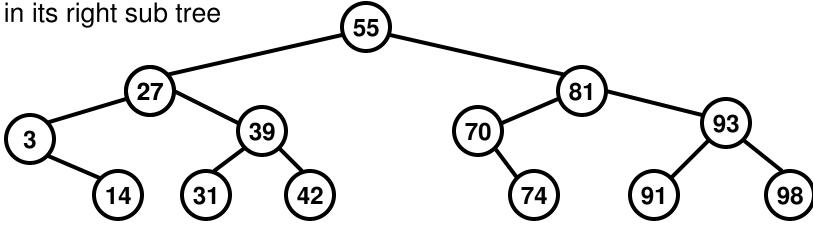
declare the search key is not there.

iteration.

```
BinarySearch(A[0..n-1], K)
ALGORITHM
                                                          Note that the "search space"
    //Implements nonrecursive binary search
                                                                 reduces by half in each
    //Input: An array A[0..n-1] sorted in ascending order and
            a search key K
                                                               Hence, the # iterations is
    //Output: An index of the array's element that is equal to K
                                                                  proportional to log(n),
            or -1 if there is no such element
    //
                                                             where 'n' is the # elements
    l \leftarrow 0; r \leftarrow n-1
                                        The algorithm is run until the left index
    while l < r do
                                        is less than or equal to the right index
        m \leftarrow \lfloor (l+r)/2 \rfloor
                                        The search key should be found by then.
        if K = A[m] return m
        else if K < A[m] r \leftarrow m-1
                                        The moment the left index becomes
        else l \leftarrow m+1
                                        greater than the right index, we stop and
```

Binary Search Tree (BST)

• A binary search tree is a binary tree in which the value for an internal node is greater than or equal to the values of the nodes in its left sub tree.



- Both hash tables and BSTs are data structures to implement a Dictionary ADT
- A hash table is an unordered collection of data items as a hash table could be constructed for any arbitrary array and the search could be conducted on a specific linked list to which the search element indexes (hash index) into.
- A BST is an ordered collection of data items (satisfying the property mentioned above). The number of comparisons it takes for a successful search or an unsuccessful search is bounded by the height of the binary search tree, which is proportional to log(# nodes).

Algorithm to Construct a BST

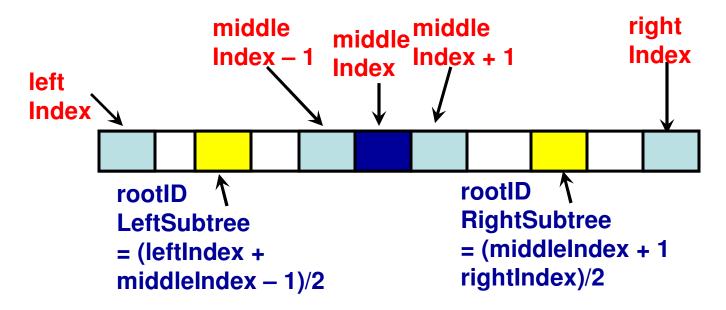
```
Begin BST Construction(Array A, numNodes)
  int leftIndex = 0
  int rightIndex = numNodes - 1
  int middleIndex = (leftIndex + rightIndex) / 2
  rootNodeID = middleIndex
  BSTree[middleIndex].setData(A[middleIndex])
  ChainNodes(A, middleIndex, leftIndex, rightIndex)
```

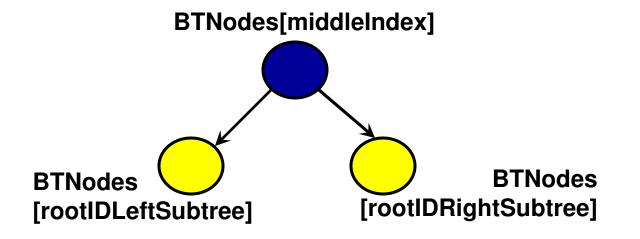
End BST Construction

left Index (numNodes – 1)
Index (0)

rootNodeID

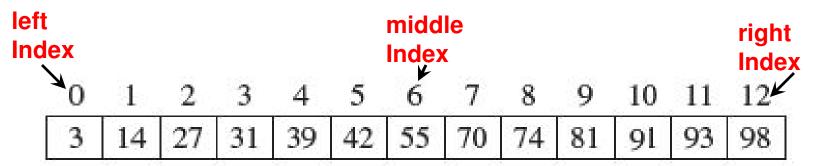
Logic behind the ChainNodes Function

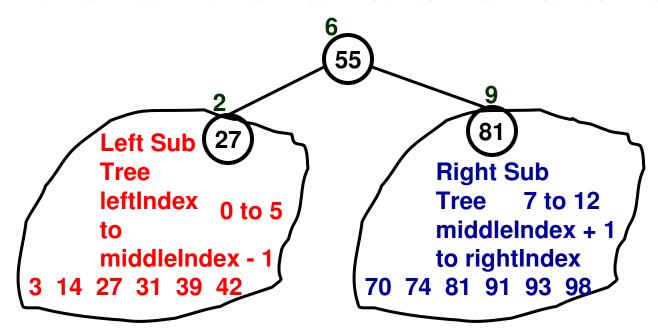


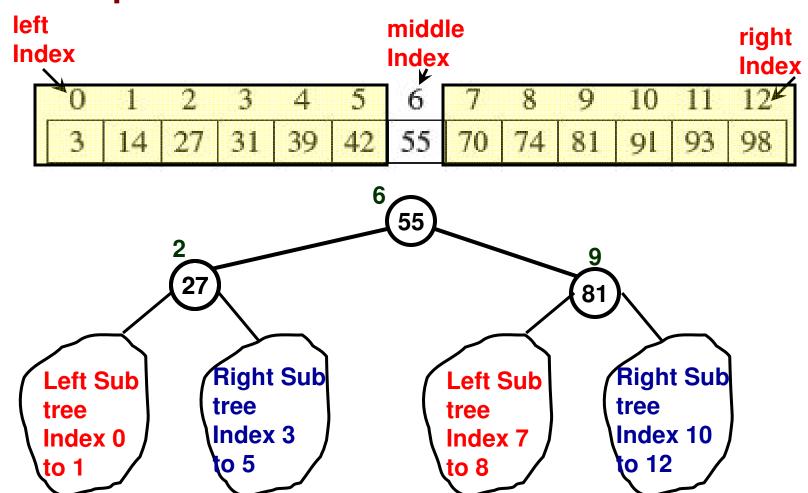


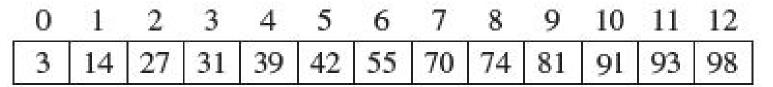
Pseudo Code: ChainNodes Function

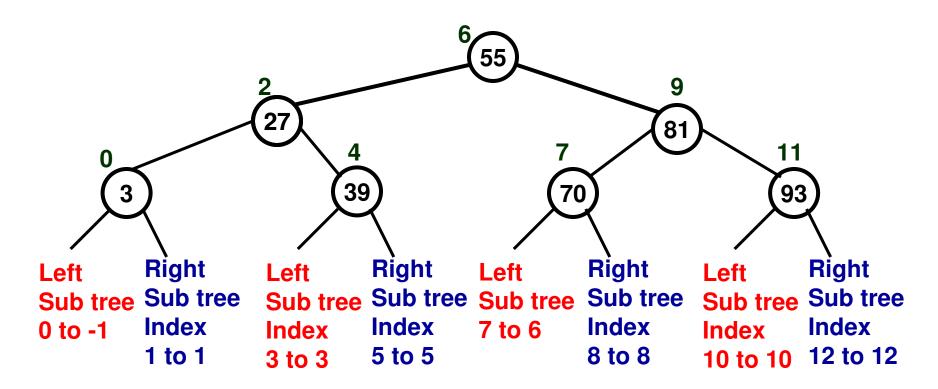
```
ChainNodes(A, middleIndex, leftIndex, rightIndex)
   if (leftIndex < middleIndex) then // a left sub tree exists for the node
                                        // at middleIndex
        rootIDLeftSubtree = (leftIndex + middleIndex - 1) / 2
        BTNodes[rootIDLeftSubtree].setData(A[rootIDLeftSubtree])
        setLeftLink(middleIndex, rootIDLeftSubtree)
        ChainNodes(A, rootIDLeftSubtree, leftIndex, middleIndex – 1)
   end if
   if (rightIndex > middleIndex) then // a right sub tree exists for the node
                                        // at middleIndex
        rootIDRightSubtree = (middleIndex + 1 + rightIndex) / 2
        BTNodes[rootIDRightSubtree].setData(A[rootIDRightSubtree])
        setRightLink(middleIndex, rootIDRightSubtree)
        ChainNodes(A, rootIDRightSubtree, middleIndex + 1, rightIndex)
   end if
```

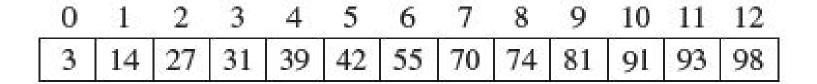


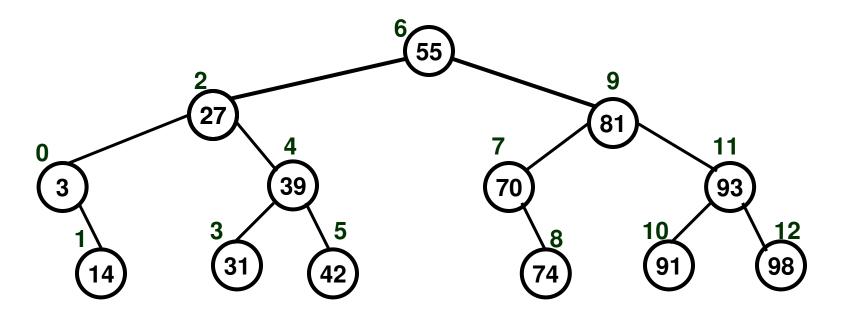


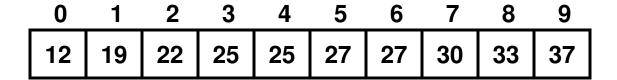


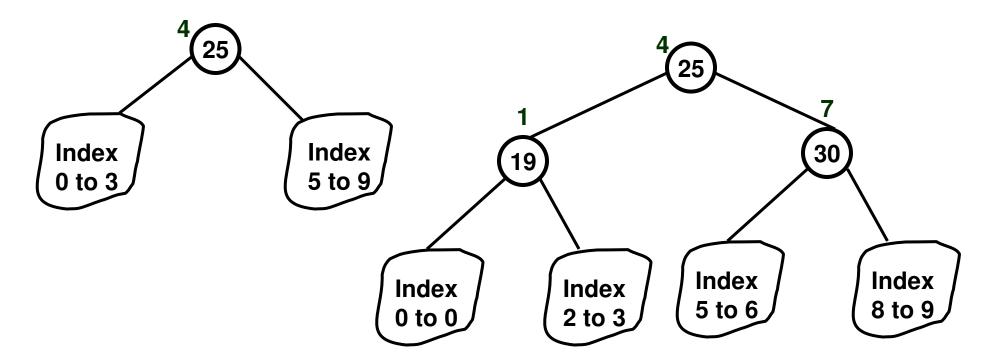


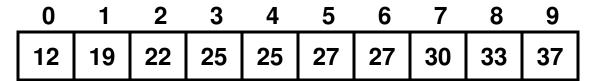


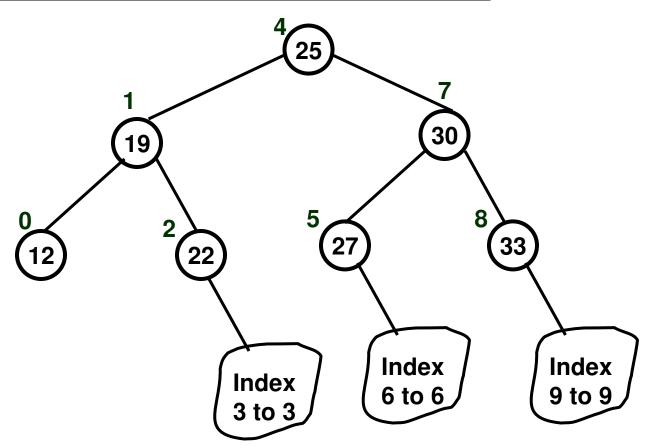


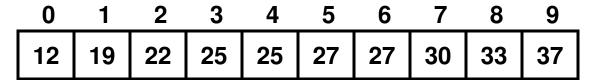


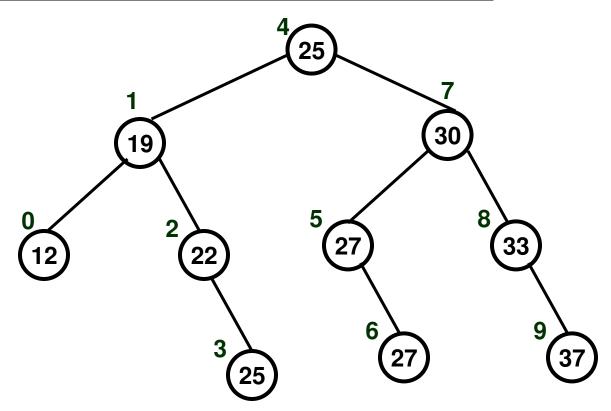












Binary Search Tree (BST) Construction

- We will create a class called BinarySearchTree that will be similar to the BinaryTree class created in the other module as much as possible.
- Differences
 - There will be a member variable called root node id (the root node id of a BST need not be 0)
 - We will add two member functions called constructBSTree() that will get the input array of sorted integers from the user, determines the root node and calls the ChainNodes(...) function, which is implemented in a recursive fashion.
 - The ChainNodes(...) function will link a node to its left child node and right child node, if any exists, and will call itself to do the same on its left sub tree and right sub tree.

BST Implementation (C++: Code 7.1)

BTNode

int nodeid int data int levelNum BTNode* leftChildPtr BTNode* rightChildPtr

BinarySearchTree

int numNodes
BTNode* arrayOfBTNodes
int rootNodeID

```
BinarySearchTree(int n){
    numNodes = n;
    arrayOfBTNodes = new BTNode[numNodes];

for (int index = 0; index < numNodes; index++){
    arrayOfBTNodes[index].setNodeId(index);
    arrayOfBTNodes[index].setLeftChildPtr(0);
    arrayOfBTNodes[index].setRightChildPtr(0);
    arrayOfBTNodes[index].setLevelNum(-1);
}
}
```

```
void setLeftLink(int upstreamNodeID, int downstreamNodeID){
    arrayOfBTNodes[upstreamNodeID].setLeftChildPtr(&arrayOfBTNodes[downstreamNodeID]);
}

void setRightLink(int upstreamNodeID, int downstreamNodeID){
    arrayOfBTNodes[upstreamNodeID].setRightChildPtr(&arrayOfBTNodes[downstreamNodeID]);
}
```

constructBSTree Function (Code 7.1)

```
void constructBSTree(int* array){
    int leftIndex = 0;
    int rightIndex = numNodes-1;
    int middleIndex = (leftIndex + rightIndex)/2;
    is already sorted

rootNodeID = middleIndex;
    arrayOfBTNodes[middleIndex].setData(array[middleIndex]);

ChainNodes(array, middleIndex, leftIndex, rightIndex);
}
ChainNodes(array, middleIndex, leftIndex, rightIndex);
```

ChainNodes Function (C++ Code 7.1)

```
void ChainNodes(int* array, int middleIndex, int leftIndex, int rightIndex){
      if (leftIndex < middleIndex){</pre>
             int rootIDLeftSubtree = (leftIndex + middleIndex-1)/2;
             setLeftLink(middleIndex, rootIDLeftSubtree);
             arrayOfBTNodes[rootIDLeftSubtree].setData(array[rootIDLeftSubtree]);
             ChainNodes(array, rootIDLeftSubtree, leftIndex, middleIndex-1);
      if (rightIndex > middleIndex){
             int rootIDRightSubtree = (rightIndex + middleIndex + 1)/2;
             setRightLink(middleIndex, rootIDRightSubtree);
             arrayOfBTNodes[rootIDRightSubtree].setData(array[rootIDRightSubtree]);
             ChainNodes(array, rootIDRightSubtree, middleIndex+1, rightIndex);
```

constructBSTree Function (called without the data array)

```
void constructBSTree(){
    int leftIndex = 0;
    int rightIndex = numNodes-1;
    int middleIndex = (leftIndex + rightIndex)/2;
    rootNodeID = middleIndex;
    ChainNodes(middleIndex, leftIndex, rightIndex);
}
```

ChainNodes Function (called without the data array)

```
void ChainNodes(int middleIndex, int leftIndex, int rightIndex){
       if (leftIndex < middleIndex){</pre>
               int rootIDLeftSubtree = (leftIndex + middleIndex-1)/2;
               setLeftLink(middleIndex, rootIDLeftSubtree);
               ChainNodes(rootIDLeftSubtree, leftIndex, middleIndex-1);
       if (rightIndex > middleIndex){
               int rootIDRightSubtree = (rightIndex + middleIndex + 1)/2;
               setRightLink(middleIndex, rootIDRightSubtree);
               ChainNodes(rootIDRightSubtree, middleIndex+1, rightIndex);
```

Selection Sort: Example

| Given Array: 12 | 5 | 1 | | 4 | 1 | 18 | | 9 | 7 | | 15 | | | |
|-----------------|----------|---|---|---|----|----|----|---|----|---|----|----|----|--|
| | Index: 0 | | 1 | | 2 | | 3 | | 4 | | 5 | 6 | 7 | |
| | Data: 12 | | 5 | | 1 | | 4 | | 18 | , | 9 | 7 | 15 | |
| Iteration 0 | 1 | | 5 | | 12 | | 4 | | 18 | Ç | 9 | 7 | 15 | |
| Iteration 1 | 1 | | 4 | | 12 | | 5 | | 18 | 9 | 9 | 7 | 15 | |
| Iteration 2 | 1 | | 4 | | 5 | | 12 | | 18 | | 9 | 7 | 15 | |
| Iteration 3 | 1 | | 4 | | 5 | | 7 | | 18 | | 9 | 12 | 15 | |
| Iteration 4 | 1 | | 4 | | 5 | | 7 | | 9 | - | 18 | 12 | 15 | |
| Iteration 5 | 1 | | 4 | | 5 | | 7 | | 9 | - | 12 | 18 | 15 | |
| Iteration 6 | 1 | | 4 | | 5 | | 7 | | 9 | 1 | 12 | 15 | 18 | |

Code 7.2 Selection Sort (C++)

```
void selectionSort(int *array, int arraySize){
      for (int iterationNum = 0; iterationNum < arraySize-1; iterationNum++){
             int minIndex = iterationNum;
             for (int j = iterationNum+1; j < arraySize; j++){
                    if (array[i] < array[minIndex])
                           minIndex = j;
             // swap array[minIndex] with array[iterationNum]
             int temp = array[minIndex];
             array[minIndex] = array[iterationNum];
             array[iterationNum] = temp;
```

```
int numElements;
cout << "Enter the number of elements: ";
cin >> numElements;
int *array = new int[numNodes];
int maxValue;
cout << "Enter the maximum value for an element: ";
cin >> maxValue;
srand(time(NULL));
cout << "array generated: ";
for (int index = 0; index < numNodes; index++)\{
      array[index] = rand() % maxValue;
                                  Main Function for BST
      cout << array[index] << " ";
}
                                           Implementation
cout << endl:
                                   based on a Randomly
selectionSort(array, numNodes);
                          Generated and Sorted Array
BinarySearchTree bsTree(numElements);
                                          (Code 7.3: C++)
bsTree.constructBSTree(array);
```

getIndex(int searchKey) Method C++ Code: 7.4

```
int getKevIndex(int searchKev){
      int searchNodeID = rootNodeID;
      while (searchNodeID != -1){
             if (searchKey == arrayOfBTNodes[searchNodeID].getData())
                   return searchNodeID;
             else if (searchKey < arrayOfBTNodes[searchNodeID].getData())
                   searchNodeID = arrayOfBTNodes[searchNodeID].getLeftChildID();
             else
                   searchNodeID = arrayOfBTNodes[searchNodeID].getRightChildID();
      return -1;
```

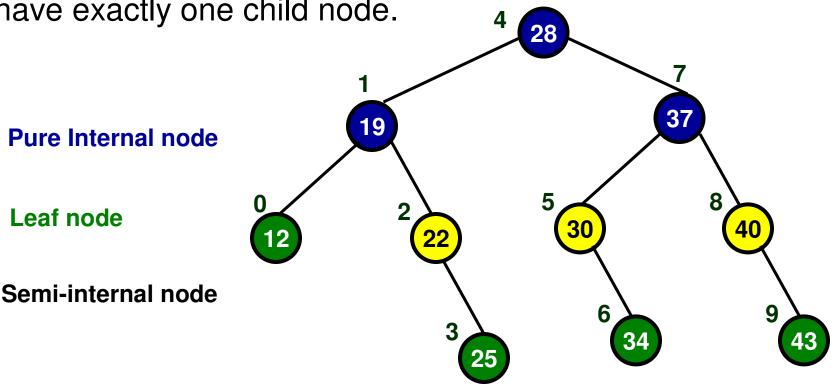
Avg. # Comparisons: Successful Search and Unsuccessful Search

A leaf node is a node with no child nodes

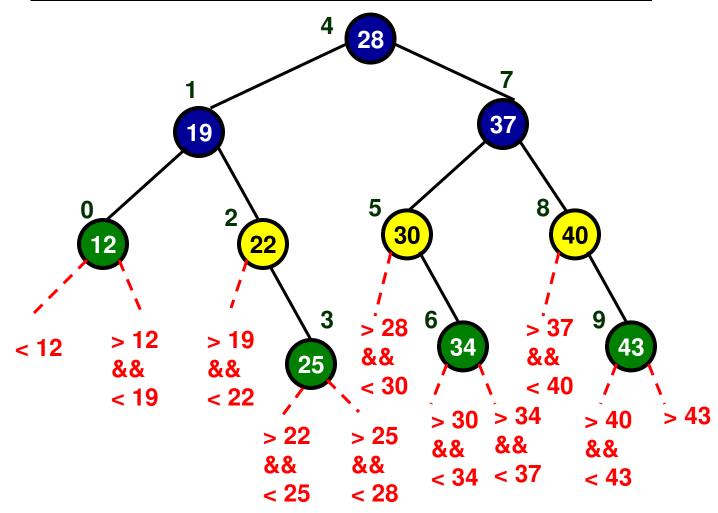
Leaf node

 Let us refer to a node as a "pure internal node" if it has both a left child as well as a right child.

 A "semi-internal node" is a node that is not a leaf node as well as not a pure internal node and is considered to have exactly one child node.



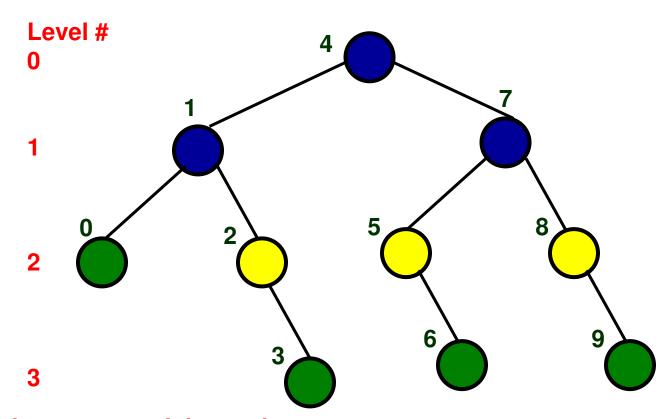
- A successful search is a search for a data that corresponds to one of the nodes in the BST.
- An unsuccessful search is a search for a missing data that if at all present could be in either the left or right sub tree of a leaf node or in the missing sub tree of a semi-internal node.
 - Each such missing sub trees would constitute a range in which the data for an unsuccessful search could be located.



Avg. # Comparisons based only on the Structure of the BST

Successful Search
Comparisons for
a node is
1 + the level number
for the node

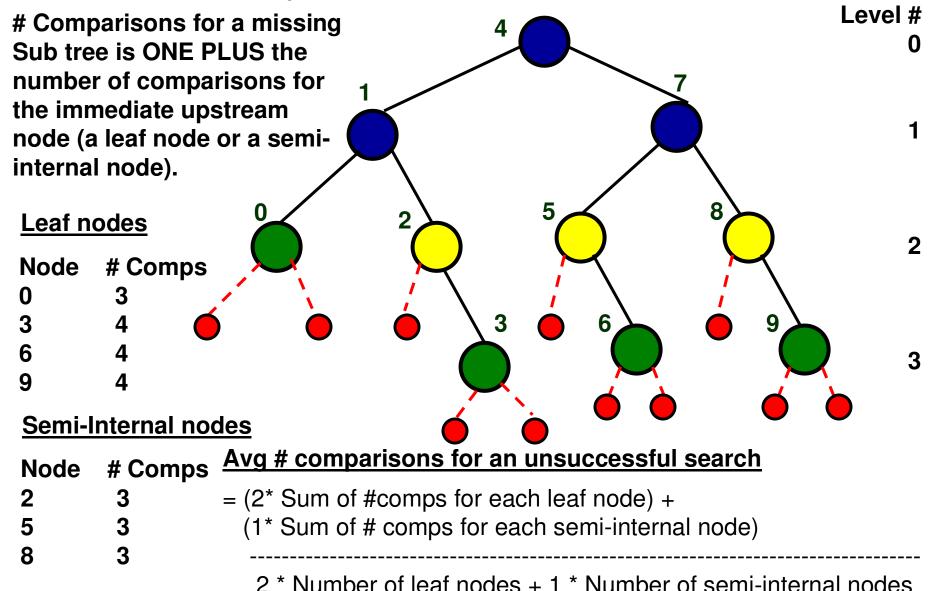
| # Comp | # Nodes |
|--------|---------|
| 1 | 1 |
| 2 | 2 |
| 3 | 4 |
| 4 | 3 |

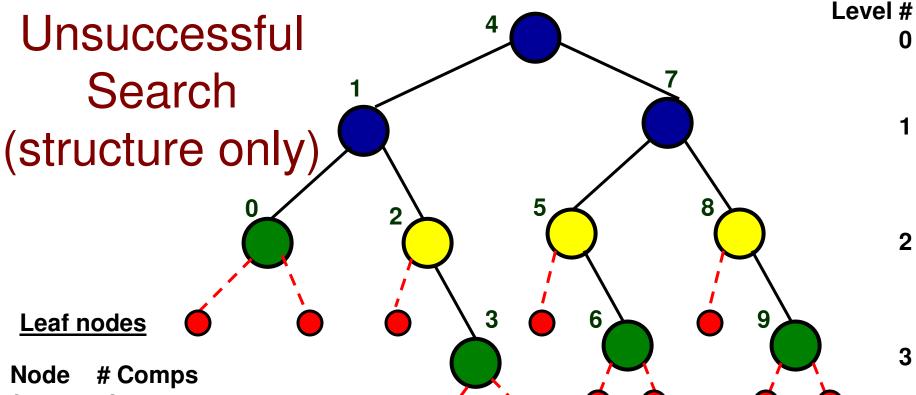


Average # Comparisons for a successful search

Level 0 Level 1 Level 2 Level 3 $\frac{(1 \text{ comp * 1 node}) + (2 \text{ comp * 2 nodes}) * (3 \text{ comp * 4 nodes}) + (4 \text{ comp * 3 nodes})}{\text{Total number of nodes (10)}}$

Avg # Comparisons: Unsuccessful Search based only on the Structure of the BST





| Node | # Comp |
|------|--------|
| 0 | 3 |
| 3 | 4 |
| 6 | 4 |
| ۵ | 1 |

Semi-Internal nodes

| Node | # Comps |
|------|---------|
| 2 | 3 |
| 5 | 3 |
| 8 | 3 |
| | |

Avg # comparisons for an unsuccessful search

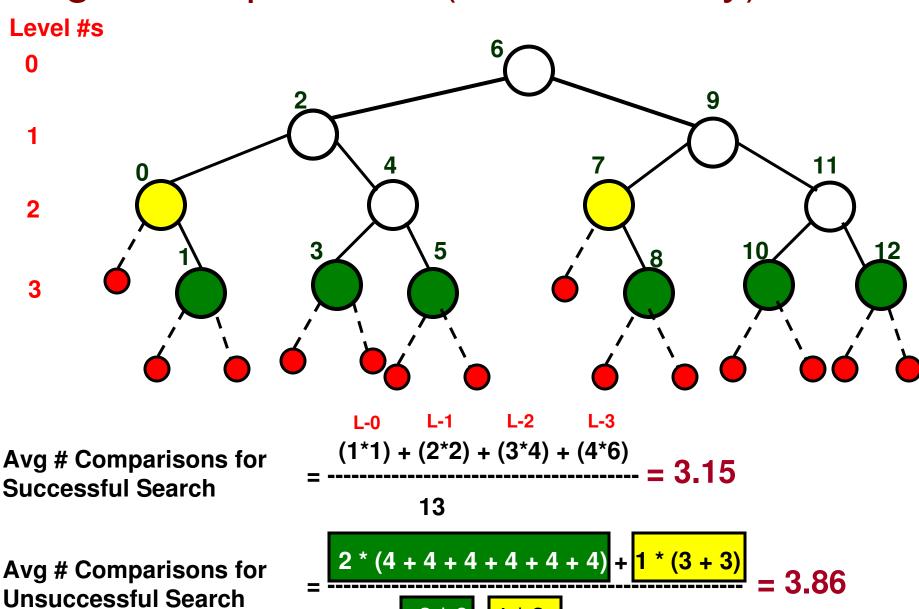
(2* Sum of #comps for each leaf node) +

(1* Sum of # comps for each semi-internal node)

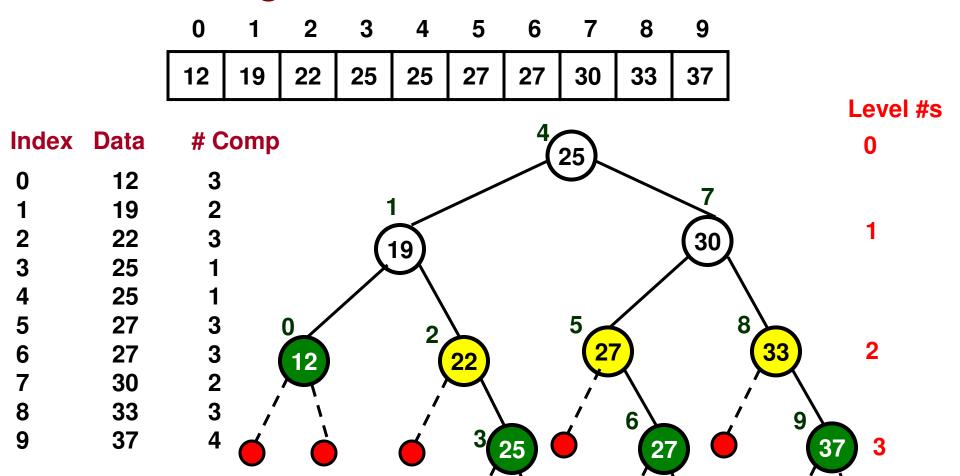
2 * # leaf nodes + 1 * # semi-internal nodes

$$= \frac{2*(3+4+4+4)+1*(3+3+3)}{(2*4+1*3)} = 3.55$$

Avg # Comparisons (structure only): Ex. 2

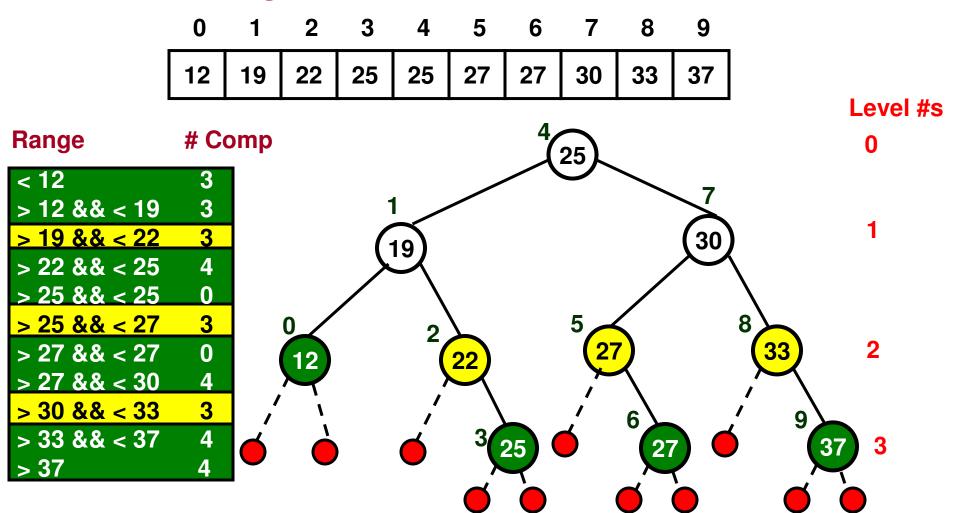


Considering both structure and data: Ex. 1



Avg. # Comparisons for
$$(3+2+3+1+1+3+3+2+3+4)$$
 = 2.50 a Successful Search

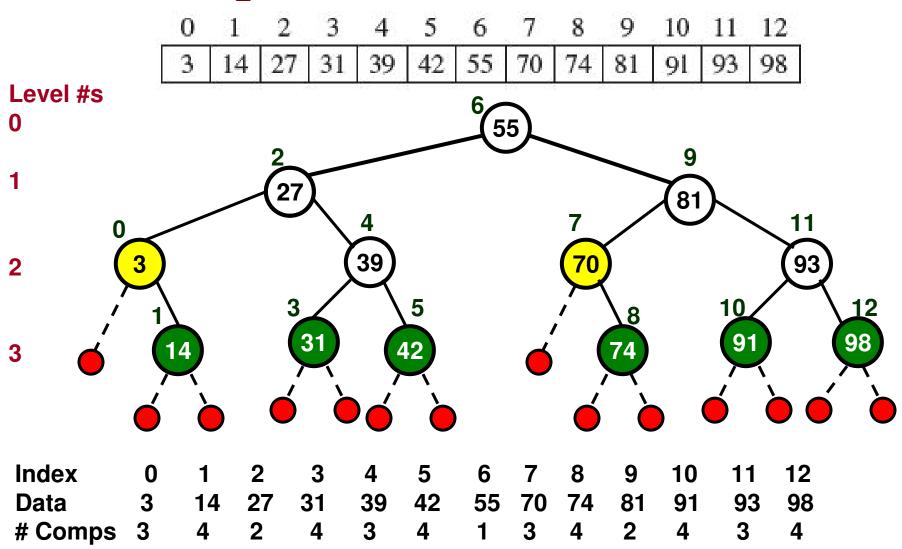
Considering both structure and data: Ex. 1



Avg. # Comparisons for
$$(3+3+3+4+3+4+3+4+4)$$
 = 3.44 an Unsuccessful Search 9

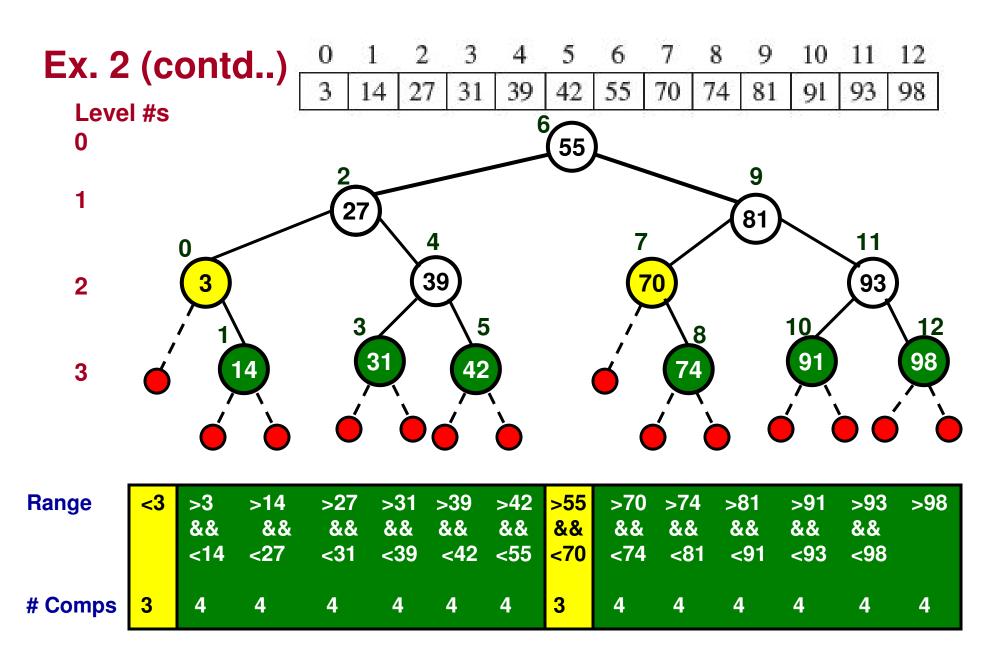
(Considering only the ranges for which the # comparisons is > 0)

Considering both structure and data: Ex. 2



Avg. # Comparisons for a Successful Search

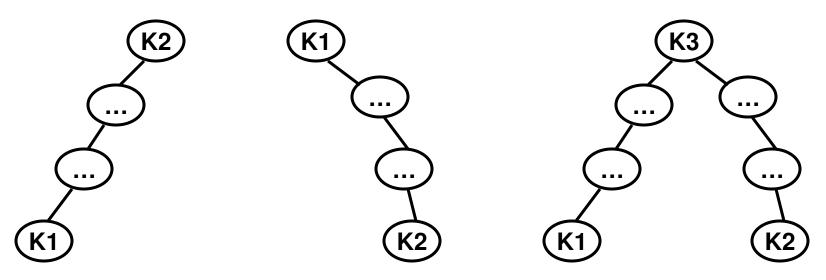
$$= \frac{(3+4+2+4+3+4+1+3+4+2+4+3+4)}{13} = 3.15$$



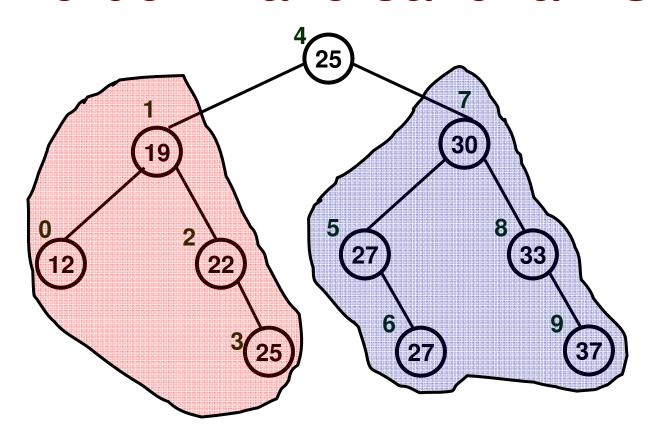
Avg. # Comparisons for An Unsuccessful Search

inorder Traversal of a BST (see Code 7.3)

- inorder traversal of a BST will list the keys of the BST in a sorted order.
- Proof: Let K1 < K2 be the two keys in a BST. We want to prove that K1 will appear before K2 in an inorder traversal of the BST.
- There are three scenarios:
 - K2 is in the right sub tree of K1
 - K1 is in the left sub tree of K2
 - K1 and K2 have a common ancestor (say K3) such that K1 < K3 < K2.
- For each of the three scenarios, if we were to do an inorder traversal, K1 will appear before K2.



inorder Traversal of a BST



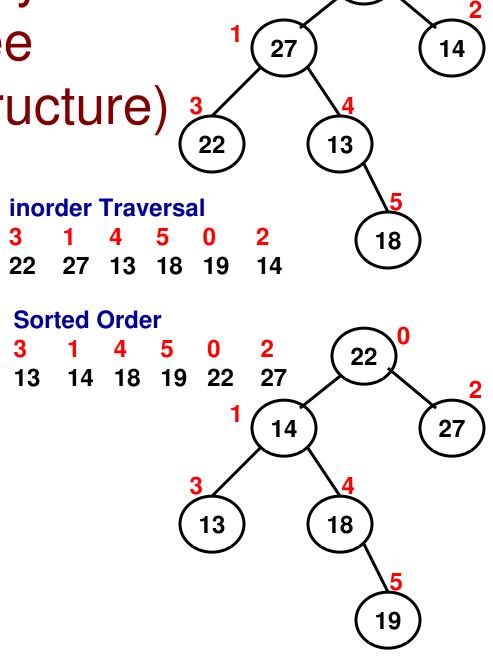
{Left sub tree} {root} {Right sub tree}

| Left su | ıb tree | Root | Right sub tree | | | | | | |
|---------|---------|------|----------------|----|----|----|--|--|--|
| 0 1 | 2 3 | 4 | 5 6 | 7 | 8 | 9 | | | |
| 12 19 | 22 25 | 25 | 27 27 | 30 | 33 | 37 | | | |

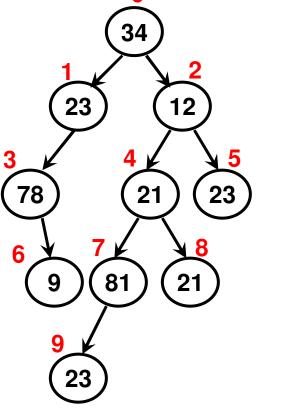
Converting a Binary Tree to a Binary Search Tree

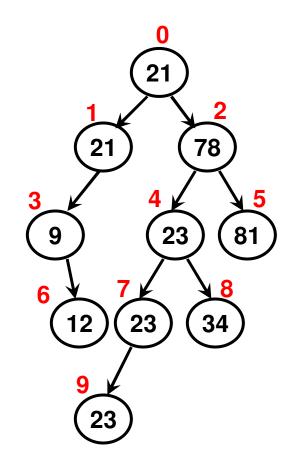
(preserving the structure)

- Do an inorder traversal of the given binary tree and get an array of data corresponding to the nodes of the tree in the order they are visited (i.e., the index entries of the nodes)
- Sort the data using a sorting algorithm
- Do an inorder traversal of the binary tree again. For each node that is about to be listed (as per the index entries), replace their data with the data in the sorted array.



Converting a Binary Tree to a BST: Example 2





inorder Traversal 3 6 1 0 9 7 4 8 2 5

78 9 23 34 23 81 21 21 12 23

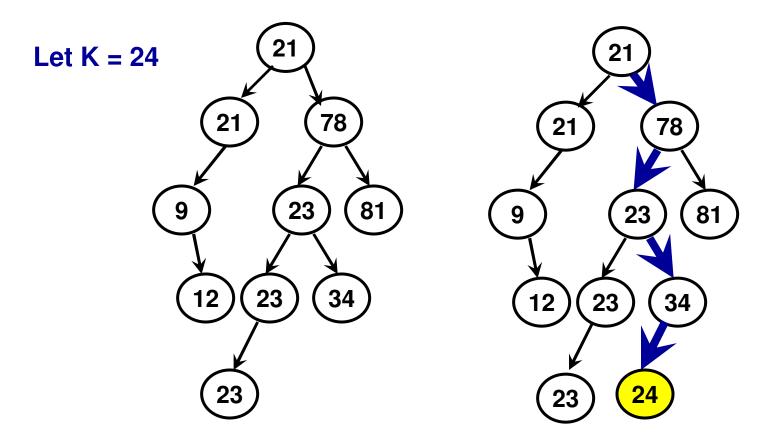
Sorted Order of the inorder Traversed Data

 3
 6
 1
 0
 9
 7
 4
 8
 2
 5

 9
 12
 21
 21
 23
 23
 23
 34
 78
 81

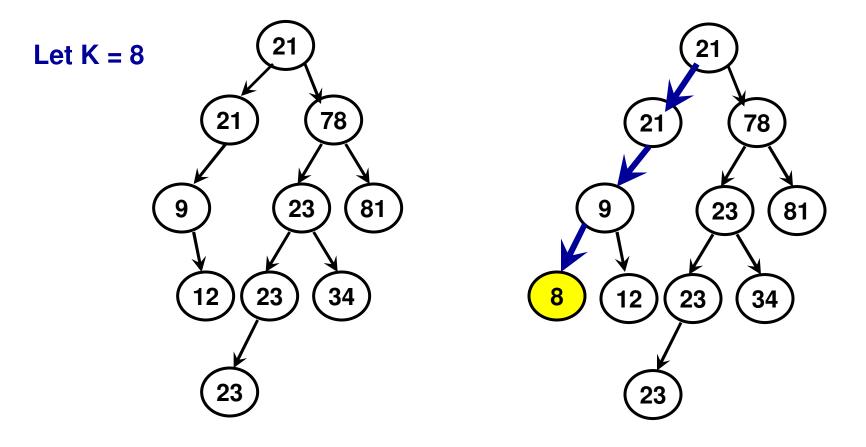
Inserting an Element in a BST (1)

 Let K be the data to be inserted. Traverse the BST as if we are searching for the data element K. When we come to a leaf node or a semi-internal node, we insert to its left or right depending on the case. If there is a tie, we insert a node as the left child.



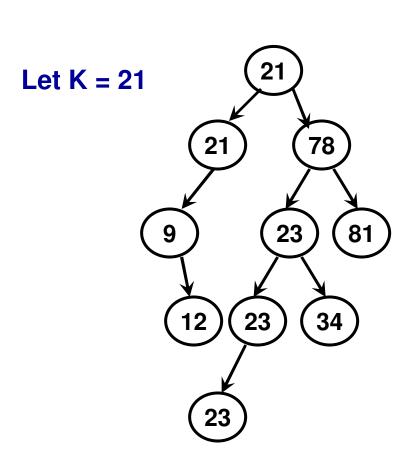
Inserting an Element in a BST (2)

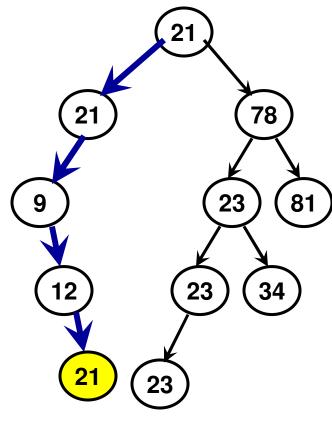
 Let K be the data to be inserted. Traverse the BST as if we are searching for the data element K. When we come to a leaf node or a semi-internal node, we insert to its left or right depending on the case. If there is a tie, we insert a node as the left child.



Inserting an Element in a BST (3)

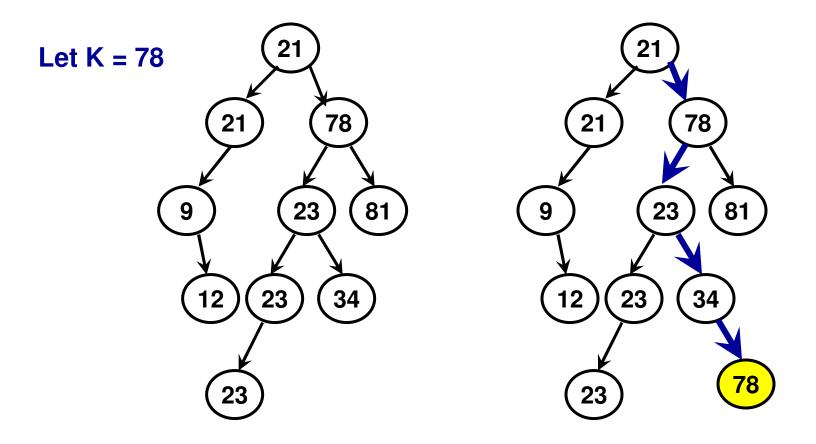
• If the data to insert is already there, then proceed to its left sub tree. Traverse the left sub tree as if you are searching for the data in the sub tree. Follow the rules for insertion as mentioned before.





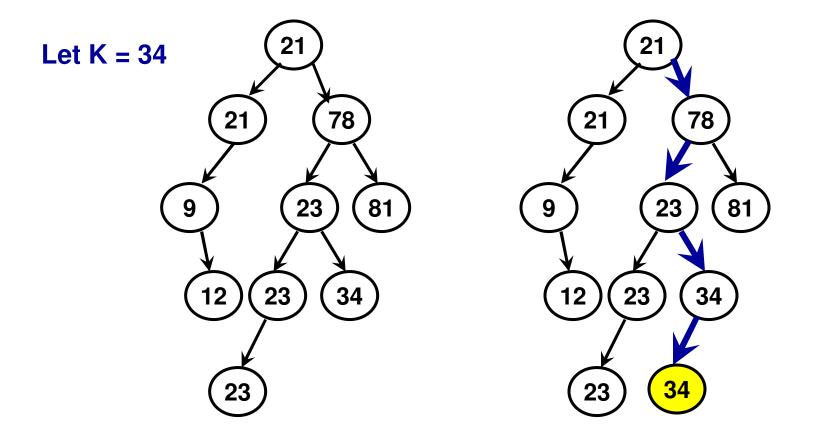
Inserting an Element in a BST (4)

• If the data to insert is already there, then proceed to its left sub tree. Traverse the left sub tree as if you are searching for the data in the sub tree. Follow the rules for insertion as mentioned before.



Inserting an Element in a BST (5)

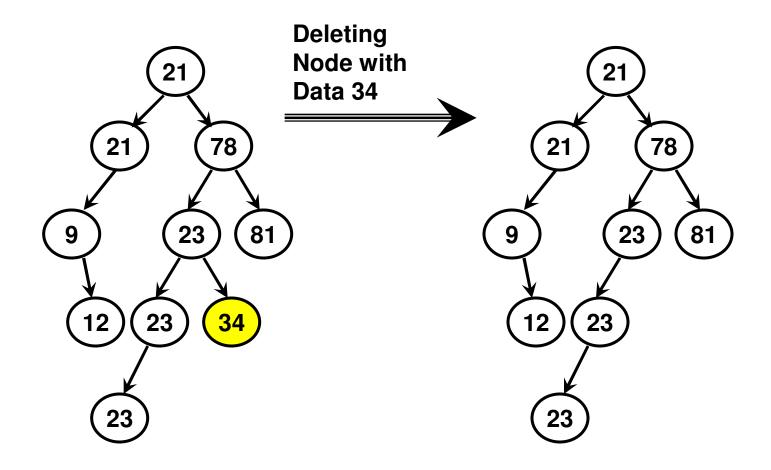
• If the data to insert is already there, then proceed to its left sub tree. Traverse the left sub tree as if you are searching for the data in the sub tree. Follow the rules for insertion as mentioned before.



- Three scenarios arise
 - Scenario 1: The node to be deleted is a leaf node:
 - Just delete the node from the BST
 - Scenario 2: The node to be deleted has only one child node (i.e., is a semi-internal node)
 - Replace the node to be deleted with the child node and its sub tree, if any exists
 - Scenario 3: The node to be deleted has two child nodes: Find the inorder successor of the node to be deleted
 - <u>Scenario 3.1:</u> If the inorder successor is a leaf node, simply copy its value to the node to be deleted and delete the inorder successor.
 - Scenario 3.2: If the inorder successor is an internal node (other than the root), then copy its value to the node to be deleted and link the sub tree rooted at the inorder successor to be the left sub tree of the parent node of the inorder successor.

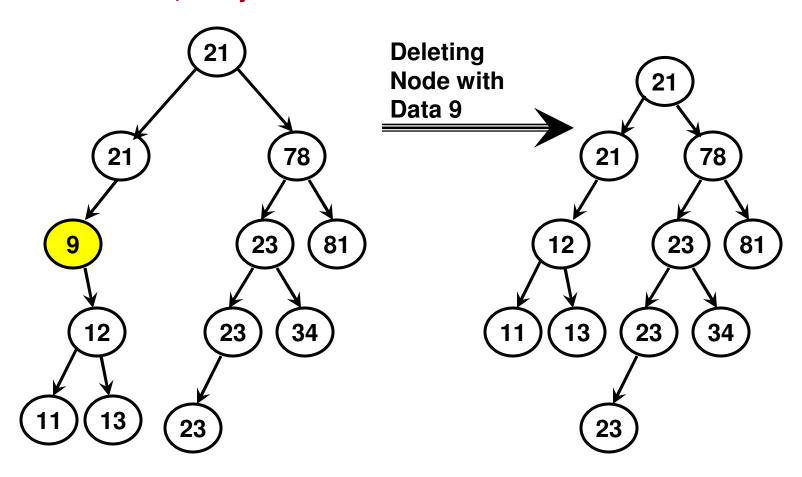
(Scenario 1: Deleting a leaf node)

Rule: Just delete the node from the BST



(Scenario 2: Deleting a semi-internal node: an internal node with one child node)

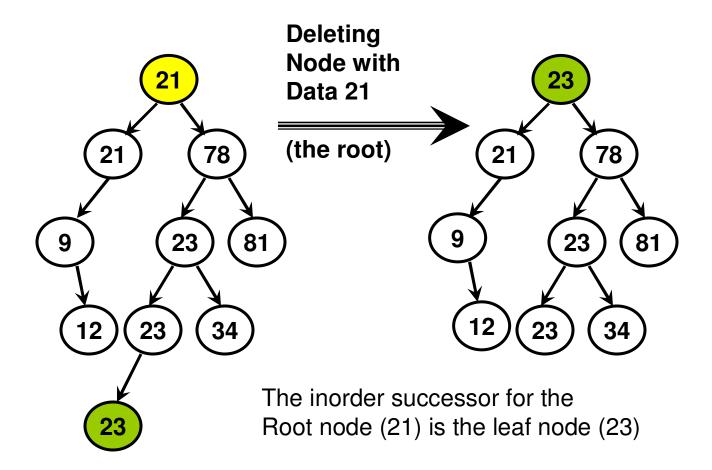
Rule: Replace the node to be deleted with the child node and its sub tree, if any exists



(Scenario 3: Deleting a "pure" internal node with two child nodes)

Scenario 3.1: The inorder successor is a leaf node

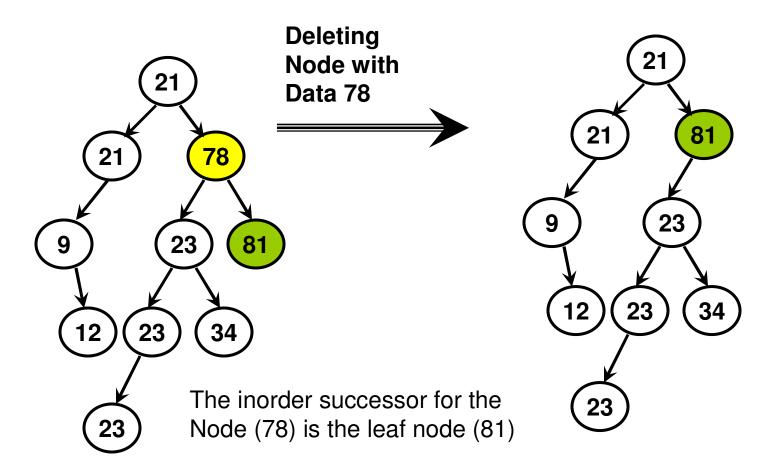
Rule: Simply copy the value of the inorder successor to the node to be deleted and delete the inorder successor.



(Scenario 3: Deleting a "pure" internal node with two child nodes)

Scenario 3.1: The inorder successor is a leaf node

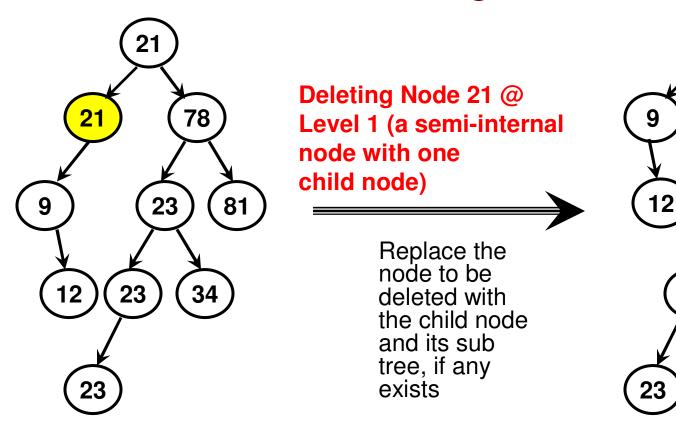
Rule: Simply copy the value of the inorder successor to the node to be deleted and delete the inorder successor.

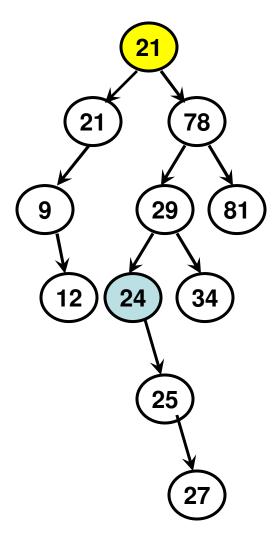


(Scenario 3: Deleting a "pure" internal node with two child nodes)

Scenario 3.2: The inorder successor is not a leaf node

Deleting Rule: If the inorder successor **Node with** is an internal node Data 23 21 (other than the root), **78** (@ level 2) then copy its 21 **78** value to the node to 81 be deleted and link 9 the sub tree rooted 81 at the 34 inorder successor to 12 23 be the left sub tree 34 12 of the parent node of the 37 inorder successor. **37** 23 Node '31'@ level 4 is the Inorder successor and its 33 parent node is Node '34' @ level 3.





Deleting Node 21 (the root) (an internal node with two child nodes)

If the inorder successor is an internal node, then copy its value to the node to be deleted and link the sub tree rooted at the inorder successor to be the left sub tree of the parent node of the inorder successor.

